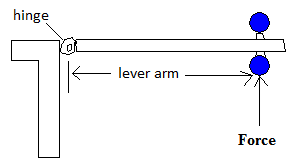
**PHYS 102 L9 TORQUE**Name:\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

Purpose: To investigate torque by doing the following activities:  
    a. Measuring an unknown mass                                               
    b. Measuring the mass of a meter stick  
    c. Solving a mobile problem

Apparatus: Meter stick, unknown mass, knife edge clamp, knife edge support, mass-hanger, mass set, lab jack, electronic balance, and string loops.

Theory: Introduction to torque

    Think about the everyday activity of opening a door, just for a moment.



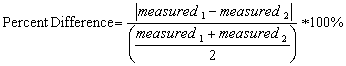
Q: What do you think you do to the door, when you open it?

A: You apply a torque.

Torque = Lever-arm X Force; Torque is a vector. Torque comes in clockwise and counter clockwise directions. Clockwise direction is the direction in which a mechanical clock turns. The opposite direction is called counter clockwise.

The door knob is kept away from the hinge in order to have a greater lever-arm. Imagine how hard it will be to open, if the knob is kept closer to the hinge.

Lever-arm is the perpendicular distance between the line of action of the force and axis of rotation.



a. Measuring an unknown mass

Meter stick is supported at the center of gravity.



Unknown mass will try to rotate the meter stick counter   
clockwise and known mass will try to rotate the meter   
stick clockwise.

For balance, counterclockwise torque = clockwise torque.

Unknown mass can be determined using the above equation.

DATA for Unknown Mass  
  
Location of the center of gravity (C.G) = \_\_\_\_\_\_\_\_ cm

Location of the unknown mass          = \_\_\_\_\_\_\_\_\_ cm    \_\_\_\_\_\_\_\_\_cm    \_\_\_\_\_\_\_\_\_\_cm

Location of the known mass              = \_\_\_\_\_\_\_\_\_ cm    \_\_\_\_\_\_\_\_\_cm    \_\_\_\_\_\_\_\_\_\_cm

|  |  |  |  |
| --- | --- | --- | --- |
| Known mass, M2 (g) | Moment-arm for known mass, MA-2 | Moment-arm for unknown mass, MA-1 | Unknown mass, M1 |
| 200 | - | - | - |
| 250 | - | - | - |
| 300 | - | - | - |
| Average of the unknown mass, M1 | | | - |
| Unknown mass measured using electronic balance | | | - |
| % difference | | | - |

b. Measuring the mass of a meter stick (M)

Now you need to move the support point away from the center of gravity (C.G). This way you get the rotation effect of M, mass of the meter stick.



DATA for Mass of Meter Stick

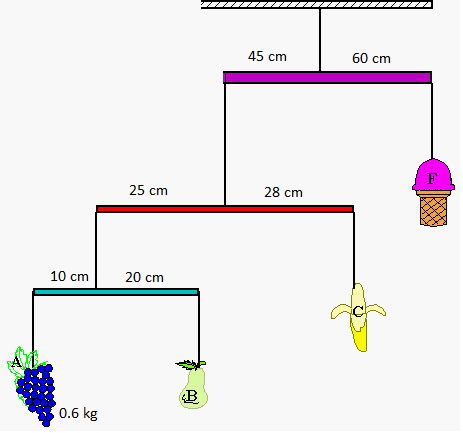
Location of the center of gravity (C.G) = \_\_\_\_\_\_\_\_ cm.

Location of the support point               = \_\_\_\_\_\_\_\_ cm    \_\_\_\_\_\_\_\_\_\_cm    \_\_\_\_\_\_\_\_\_cm

Location of the known mass                = \_\_\_\_\_\_\_\_ cm    \_\_\_\_\_\_\_\_\_\_cm    \_\_\_\_\_\_\_\_\_cm

|  |  |  |  |
| --- | --- | --- | --- |
| Known mass, m (g) | Moment-arm for known mass, l | Moment-arm for mass of meter stick, L | Mass of meter stick, M |
| 100 | - | - | - |
| 150 | - | - | - |
| 200 | - | - | - |
| Average of the mass of meter stick, M | | | - |
| Mass of meter stick measured using electronic balance | | | - |
| % difference | | | - |

C. For the mobile shown the beams have negligible masses. The mass of A is 0.6 kg. Determine the masses of B, C, and F.



Conclusion: